

Coherent states on some new fuzzy spheres

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Introduction

We have recently [Ref. below] introduced

- a fully $O(2)$ -covariant fuzzy circle $\{S_\Lambda^1\}_{\Lambda \in \mathbb{N}}$,
- a fully $O(3)$ -covariant fuzzy 2-sphere $\{S_\Lambda^2\}_{\Lambda \in \mathbb{N}}$.

We resp. start from a quantum particle in $\mathbb{R}^2, \mathbb{R}^3$ u a confining potential $V(r)$ with a very sharp minimum on the sphere of radius $r = 1$ and impose a suitable energy cutoff; cutoff and sharpness $V''(1) =: 4k$ of the potential well parametrized by (and diverge with) Λ .

1st motivation: alg. rel. covariant also under $x_i \mapsto -x_i$ (\neq Madore).

Here I wish to report on some further investigations about the geometry of these S_Λ^d :

Coherent States (CS);

Spectrum of the space coordinate operators x_i .

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$O(2)$ -equivariant fuzzy circle - The essentials

We previously constructed the $O(2)$ -equivariant fuzzy circle $\{\mathcal{A}_{\Lambda,2}\}_{\Lambda \in \mathbb{N}}$, it is a sequence of unitary irreducible representations $(\pi_{\Lambda,2}, \mathcal{H}_{\Lambda,2})$ of $Uso(3)$ and every $\mathcal{A}_{\Lambda,2}$ acts on the corresponding Hilbert space

$$\mathcal{H}_{\Lambda,2} := \text{span} \{ \psi_m \mid m \in \mathbb{Z}, -\Lambda \leq m \leq \Lambda \}.$$

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The noncommutative coordinates $x_+ := \frac{x_1 + ix_2}{\sqrt{2}}$ and $x_- := \frac{x_1 - ix_2}{\sqrt{2}}$ generate the $*$ -algebra $\mathcal{A}_{\Lambda,2}$ and their actions read

$$x_+ \psi_m = \begin{cases} \frac{b_{m+1}}{\sqrt{2}} \psi_{m+1} & \text{if } -\Lambda \leq m \leq \Lambda - 1 \\ 0 & \text{otherwise,} \end{cases}$$
$$x_- \psi_m = \begin{cases} \frac{b_m}{\sqrt{2}} \psi_{m-1} & \text{if } 1 - \Lambda \leq m \leq \Lambda \\ 0 & \text{otherwise,} \end{cases}$$

where $b_m := \sqrt{1 + \frac{m(m-1)}{k}}$.

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$L, x_+, x_-, \mathbf{x}^2$ fulfill the $O(2)$ -covariant relations

$$[L, x_{\pm}] = \pm x_{\pm}, \quad x_+^{\dagger} = x_-, \quad (L)^{\dagger} = L, \quad (1)$$

$$[x_+, x_-] = -\frac{L}{k} + \left[1 + \frac{\Lambda(\Lambda+1)}{k} \right] \frac{\tilde{P}_{\Lambda} - \tilde{P}_{-\Lambda}}{2}, \quad (2)$$

$$\mathbf{x}^2 = 1 + \frac{L^2}{k} - \left[1 + \frac{\Lambda(\Lambda+1)}{k} \right] \frac{\tilde{P}_{\Lambda} + \tilde{P}_{-\Lambda}}{2}, \quad (3)$$

$$\prod_{m=-\Lambda}^{\Lambda} (L - ml) = 0, \quad (x_{\pm})^{2\Lambda+1} = 0. \quad (4)$$

Here \tilde{P}_m is the projection over the 1-dim subspace spanned by ψ_m , and k is a sufficiently large function of Λ , for example

$$k = k(\Lambda) = \Lambda^2(\Lambda+1)^2.$$

$O(3)$ -equivariant fuzzy sphere - The essentials

We previously built a $O(3)$ -equivariant fuzzy sphere, formed by a sequence $\{\mathcal{A}_{\Lambda,3}\}_{\Lambda \in \mathbb{N}}$ of unitary irreducible representations $(\pi_{\Lambda,3}, \mathcal{H}_{\Lambda,3})$ of $Uso(4)$ and the corresponding representation spaces were denoted by

$$\mathcal{H}_{\Lambda,3} := \text{span} \{ \psi_l^m \mid l \in \mathbb{N}_0, m \in \mathbb{Z}, l \leq \Lambda, |m| \leq l \}, \quad \text{where } \Lambda \in \mathbb{N}.$$

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The angular momentum operators $\{L_a\}$ and the coordinate operators $\{x_a\}$ (here $a = 0, +, -$) are obtained from the corresponding ones $\{L_i\}_{i=1}^3$ and $\{x_i\}_{i=1}^3$ as follows:

$$L_{\pm} := \frac{L_1 \pm iL_2}{\sqrt{2}}, \quad L_0 := L_3, \quad x_{\pm} := \frac{x_1 \pm ix_2}{\sqrt{2}}, \quad x_0 := x_3.$$

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Furthermore, their action is

$$L_0 \psi_l^m = m \psi_l^m, \quad L_{\pm} \psi_l^m = \frac{\sqrt{(l \mp m)(l \pm m + 1)}}{\sqrt{2}} \psi_l^{m \pm 1}, \quad (5)$$

$$x_a \psi_l^m = \begin{cases} c_l A_l^{a,m} \psi_{l-1}^{m+a} + c_{l+1} B_l^{a,m} \psi_{l+1}^{m+a} & \text{if } l < \Lambda, \\ c_\Lambda A_\Lambda^{a,m} \psi_{\Lambda-1}^{m+a} & \text{if } l = \Lambda, \\ 0 & \text{otherwise,} \end{cases} \quad (6)$$

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where $A_l^{a,m} = B_{l-1}^{-a,m-a}$ and

$$A_l^{0,m} = \sqrt{\frac{(l+m)(l-m)}{(2l+1)(2l-1)}}, \quad A_l^{\pm,m} = \frac{\pm 1}{\sqrt{2}} \sqrt{\frac{(l \mp m)(l \mp m - 1)}{(2l-1)(2l+1)}}, \quad (7)$$

$$c_l := \sqrt{1 + \frac{l^2}{k}} \quad 1 \leq l \leq \Lambda, \quad c_0 = c_{\Lambda+1} = 0, \quad (8)$$

with $k = k(\Lambda) = \Lambda^2 (\Lambda + 1)^2$

Moreover, we introduced the operator $\mathbf{x}^2 := x_i x_i = x_a x_{-a}$, which represents the square distance from the origin, and we showed that

$$\mathbf{x}^2 = 1 + \frac{L^2 + 1}{k} - \left[1 + \frac{(\Lambda + 1)^2}{k} \right] \frac{\Lambda + 1}{2\Lambda + 1} \tilde{P}_\Lambda \quad (9)$$

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In conclusion, we proved that

$$x_i^\dagger = x_i, \quad L_i^\dagger = L_i, \quad [L_i, x_j] = i\varepsilon^{ijh} x_h, \quad [L_i, L_j] = i\varepsilon^{ijh} L_h, \quad x_i L_i = 0$$

$$[x_i, x_j] = i\varepsilon^{ijh} \left(-\frac{l}{k} + K \tilde{P}_\Lambda \right) L_h \quad i, j, h \in \{1, 2, 3\},$$

$$\prod_{l=0}^{\Lambda} [L^2 - l(l + 1)l] = 0, \quad \prod_{m=-l}^l (L_3 - ml) \tilde{P}_l = 0, \quad (x_\pm)^{2\Lambda+1} = 0.$$

Coherent states - Preliminaries

The notion of coherent states (CS) has arisen with the problem of saturating the quantum uncertainty relation (UR) on \mathbb{R}^D ; on other manifolds M nontrivial problem! On $M = \mathbb{R}^D$ CS make up an overcomplete set in $\mathcal{H} := \mathcal{L}^2(\mathbb{R}^D)$ yielding a nice resolution of the identity. These properties are usually taken as minimal requirements for defining CS on other M . A set of coherent states $\{\phi_l\}$ is a particular set of vectors of a Hilbert space \mathcal{H} , l is an element of an appropriate label (and topological) space Ω s.t.:

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- **COMPLETENESS (RESOLUTION ON UNITY)**: $\exists dl$ s.t.

$$I = \int_{\Omega} \phi_l \langle \phi_l, \cdot \rangle dl = \int_{\Omega} |\phi_l\rangle \langle \phi_l| dl.$$

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- **(WEAKER) COMPLETENESS (TOTAL SET OF VECTORS)**:

$$\overline{\text{span}\{\phi_l : l \in \Omega\}} = \mathcal{H}.$$

Coherent states - Perelomov

In particular A. Perelomov (cf. his book) chooses $\Omega = G$: the system of CS $\{T, \phi_0\}$ is the set $\{\phi_g = T(g)\phi_0\}_{g \in \frac{G}{H}}$, where G is an arbitrary Lie group, H the isotropy subgroup of ϕ_0 , $T(g)$ is a unitary irreducible representation acting on a Hilbert space \mathcal{H} and $\phi_0 \in \mathcal{H}$.

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If there exists a left- and right-invariant measure $d\mu(g)$ on it, then every system of coherent states $\{T, \phi_0\}$ fulfills the **CONTINUITY** and **COMPLETENESS** properties.

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The system of states which is as close as possible to the classical states is obtained, according to Perelomov, once one chooses ϕ_0 as the state for which the isotropy subalgebra is maximal; in the cases of our interest those states correspond to the ones which minimize the dispersion of the quadratic Casimir C_2 .

Heisenberg UR - analog on S^1

Let $L = -i(x_1\partial_2 - x_2\partial_1)$ a.m. operator on \mathbb{R}^2 . $[L, x_1] = ix_2$,
 $[L, x_2] = -ix_1$ implies the UR

$$\Delta L^2(\Delta x_1)^2 \geq \frac{1}{4}\langle x_2 \rangle^2, \Delta L^2(\Delta x_2)^2 \geq \frac{1}{4}\langle x_1 \rangle^2 \Rightarrow \Delta L^2(\Delta \mathbf{x})^2 \geq \frac{1}{4}\langle \mathbf{x} \rangle^2;$$

valid also on $\mathcal{H} = \mathcal{L}^2(S^1)$, but under $\mathbf{x}^2 \equiv x_1^2 + x_2^2 = 1$; 3rd ineq is a lower bound for $\Delta L |\Delta \mathbf{x}|$ in phase space.

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$$I = \sum_n P_n \overset{*}{=} \int_{G/H} P_x d\mu(x), \quad P_n := \psi_n \langle \psi_n, \cdot \rangle.$$

$$G := \{(x_+)^n e^{i(aL+b)} \mid (a, b, n) \in \mathbb{R}^2 \times \mathbb{Z}\} \simeq U(1) \times U(1) \ltimes \mathbb{Z}$$

$H = \{e^{i(aL+b)}\} \simeq [U(1)]^2$ is the isotropy subgroup of ψ_0 , and

$G/H = \{(x_+)^n \mid n \in \mathbb{Z}\}$, hence * integrating over G/H amounts to summing over $n \in \mathbb{Z}$,

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$H = \{e^{i(aL+b)}\} \simeq [U(1)]^2$ is the isotropy subgroup of ψ_0 , and $G/H = \{(x_+)^n \mid n \in \mathbb{Z}\}$, hence * integrating over G/H amounts to summing over $n \in \mathbb{Z}$, and this can be applied also to our fuzzy circle. In this sense $\{T, \psi_0\}$ is a CS system.

UR on S^2

$[L_i, L_j] = i\epsilon^{ijk} L_k$, $[L_i, x^j] = i\epsilon^{ijk} x^k$ valid on $\mathcal{L}^2(\mathbb{R}^3)$, and $\mathcal{L}^2(S^2)$
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Coming back to Perelomov CS, if we take the irrep (π_Λ, V_Λ) of $Uso(3)$, characterized by

$$\mathbf{L}^2 = L_1^2 + L_2^2 + L_3^2 = \Lambda(\Lambda + 1),$$

it's easy to see that the dispersion $(\Delta \mathbf{L})^2 := \sum_i \Delta L_i^2$ of \mathbf{L} is minimal for vectors $Y_\Lambda^{\pm\Lambda}$ and its explicit value is $(\Delta \mathbf{L})_{min}^2 = \Lambda$.

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Proposition

The following UR holds on $\mathcal{L}^2(S^2)$, and is saturated by the spin (and Perelomov) CS belonging to each V_Λ , $\Lambda \in \mathbb{N}_0$.

$$\Delta \mathbf{L}^2 \geq |\langle \mathbf{L} \rangle| \quad \Leftrightarrow \quad \mathbf{L}^2 \geq |\langle \mathbf{L} \rangle| (|\langle \mathbf{L} \rangle| + 1).$$

Applying Perelomov construction one finds the resolution of the identity

$$I = c \sum_{l=0}^{\infty} \int_{SO(3)} d\mu(g) P_{l,g}, \quad P_{l,g} = \phi_{l,g} \langle \phi_{l,g}, \cdot \rangle, \quad \phi_{l,g} := T(g) Y_l^l.$$

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We can use these arguments for the Madore fuzzy sphere, because of the isomorphism

$$x_i = \frac{2L_i}{\sqrt{n^2 - 1}}, \quad i = 1, 2, 3$$

between the algebra of observables M_n and a suitable irreducible representation (π_Λ, V_Λ) of $Uso(3)$, having dimension $n = 2\Lambda + 1$.

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Also in this case the dispersion of $\mathbf{x}^2 := x_i x_i \equiv 1$ is minimal on the states $Y_\Lambda^{\pm\Lambda}$ and it is

$$(\Delta \mathbf{x})_{\min}^2 = \frac{2(n-1)}{n^2-1} = \frac{1}{\Lambda+1}. \quad (10)$$

Coherent states - Our targets

Our **first** target is give a meaningful definition of spatial dispersion $(\Delta \mathbf{x})^2$ on our fuzzy spaces, which will be a good measure of the localization of a state in configuration space \mathbb{R}^D ; so we adopt the expectation value (variance)

$$(\Delta \mathbf{x})^2 := \langle (\mathbf{x} - \langle \mathbf{x} \rangle)^2 \rangle = \langle \mathbf{x}^2 \rangle - \langle \mathbf{x} \rangle^2 = \langle \mathbf{x}^2 \rangle - \sum_{i=1}^D \langle x_i \rangle^2 \quad (11)$$

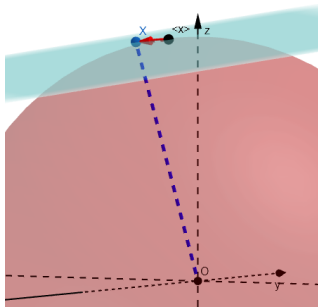
on the state;

Coherent states - Our targets

Our **first** target is give a meaningful definition of spatial dispersion $(\Delta \mathbf{x})^2$ on our fuzzy spaces, which will be a good measure of the localization of a state in configuration space \mathbb{R}^D ; so we adopt the expectation value (variance)

$$(\Delta \mathbf{x})^2 := \langle (\mathbf{x} - \langle \mathbf{x} \rangle)^2 \rangle = \langle \mathbf{x}^2 \rangle - \langle \mathbf{x} \rangle^2 = \langle \mathbf{x}^2 \rangle - \sum_{i=1}^D \langle x_i \rangle^2 \quad (11)$$

on the state; to motivate this choice we note that it is manifestly $O(D)$ -invariant and that if the state is localized in a small region $\sigma_{\langle \mathbf{x} \rangle} \subset S^d$ around a point $\langle \mathbf{x} \rangle \in S^d$ then $(\Delta \mathbf{x})^2$ essentially reduces to the average square displacement in the tangent plane at $\langle \mathbf{x} \rangle$, as one wishes.



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According to this, an analysis of $\Sigma_{x_i}(\Lambda)$ is our **second** target.

The **third** target is determine the most *localized* states of our fuzzy spaces, i.e. the ones which minimize the spatial dispersion $(\Delta \mathbf{x})^2$, and (as we will see) this target is strictly linked to the previous one.

If $\hat{\chi}$ is a state of our $O(2)$ -equivariant fuzzy circle, then the construction of Perelomov with $G \equiv SO(3)$ (which is a larger group of the algebra automorphisms), $T \equiv \pi_{\Lambda,2}$ and $\mathcal{H} \equiv \mathcal{H}_{\Lambda,2}$ returns us a system of states which fulfills the **CONTINUITY** and **COMPLETENESS** properties;

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For this reason, we try to apply the construction of Perelomov to $\hat{\chi}$ also with $G \equiv O(2)$ for the circle and $O(3)$ for the sphere. This is our **fourth** target

Coherent states - The x^i eigenvalue-problem

The covariance of the algebra under $O(D)$ transformations $\mathbf{x} \mapsto \mathbf{x}' = R\mathbf{x}$, $\mathbf{L} \mapsto \mathbf{L}' = R\mathbf{L}$ implies that the spectrum $\Sigma_{x_i}(\Lambda)$ of any coordinate operator x_i of our fuzzy spaces is the same, so we can focus our attention on the spectra of x_1 and x_3 when $D = 2$ and $D = 3$, respectively.

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For convenience, we study the eigenvalue equations

$$x_1\psi = \alpha_1\psi \text{ when } D = 2 \quad \text{and} \quad x_3\psi = \alpha_2\psi \text{ when } D = 3. \quad (12)$$

We don't need to make two different discussions, one for $D = 2$ and one for $D = 3$, for this reason now we start analyzing the three-dimensional problem.

First of all, we defined $x_0 := x_3$ and $L_0 := L_3$, but it's also true that the problem of maximizing $\langle x_0 \rangle$ is equivalent to the one of finding the maximal eigenvalue of x_0 ; in conclusion, because of $[x_0, L_0] = 0$, we can simultaneously diagonalize x_0 and L_0 .

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$$\begin{cases} L_0 \chi_\alpha^\beta = \beta \chi_\alpha^\beta \\ x_0 \chi_\alpha^\beta = \alpha \chi_\alpha^\beta \end{cases}, \quad (13)$$

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then, using (6) we can easily conclude that

$$\beta = m \in \{-\Lambda, \dots, \Lambda\} \quad \text{and} \quad \chi_\alpha^m = \sum_{l=|m|}^{\Lambda} \chi_l^m \psi_l^m. \quad (14)$$

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Proposition

If $\tilde{\alpha}$ is an eigenvalue of x_0 , then also $-\tilde{\alpha}$ must be an eigenvalue of x_0 .

We proved also that

Theorem

Let α_0 be the maximal eigenvalue of x_0 and χ_0 be the corresponding eigenvector. It is such that

$$L_0 \chi_0 = 0. \tag{15}$$

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The last theorem allows us to make a connection between our localized states and the classical ones because χ_0 describes a particle concentrated in the x_3 -direction and rotating around the x_3 -axis; then, because of the constraint on the sphere, one expects 'classically' that

$$L_3 = (\underline{L})_3 = (\underline{r} \times \underline{p})_3 = 0,$$

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Theorem

The maximal eigenvalue $\alpha_0(\Lambda)$ of x_0 fulfills

$$\lim_{\Lambda \rightarrow +\infty} \alpha_0(\Lambda) = 1.$$

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$\Sigma_{x_0}(\Lambda)$ and $\Sigma_{x_0}(\Lambda + 1)$ interlace.

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Figure 1: The spectrum $\Sigma_{x_0}(\Lambda)$ when $\Lambda = 2, \dots, 100$.

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Theorem

The spectrum $\Sigma_{x_0}(\Lambda)$ of x_0 becomes dense in $[-1, 1]$ as $\Lambda \rightarrow +\infty$.

Coherent states - Most localized states

Now we want to solve the problem of getting the most *localized* states of our fuzzy spaces, as seen previously we want to minimize $(\Delta \mathbf{x})^2$; but the $O(D)$ -covariance implies that $(\Delta \mathbf{x})^2_\psi = (\Delta R\mathbf{x})^2_\psi$ for every state $\psi \in \mathcal{H}_{\Lambda, D}$ and $O(D)$ - transformation R ;

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$$\begin{cases} (\Delta \mathbf{x})^2 = \langle \mathbf{x}^2 \rangle - \langle x_1 \rangle^2 & \text{when } D = 2, \\ (\Delta \mathbf{x})^2 = \langle \mathbf{x}^2 \rangle - \langle x_3 \rangle^2 & \text{when } D = 3. \end{cases} \quad (16)$$

On the other hand, in both dimensions $\mathbf{x}^2 = 1$ up to $\frac{1}{\Lambda^2}$, so the problem of minimizing (16)₁ is strictly linked to the one of maximizing $\langle x_1 \rangle$ for $D = 2$, as for (16)₂ and $\langle x_3 \rangle$ for $D = 3$.

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We've just studied these two *linked* problems, and from them we learned that if we calculate (when $D = 3$) $(\chi, x_0 \chi)$ on

$$\chi = \tilde{\chi} := \sum_{l=0}^{\Lambda} \tilde{\chi}^l \psi_l^0, \quad \text{with} \quad \tilde{\chi}^l = \frac{\sin \left[\frac{(l+1)\pi}{\Lambda+2} \right]}{\sqrt{\frac{\Lambda+2}{2}}} \quad \text{if } 0 \leq l \leq \Lambda,$$

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$$(\Delta \mathbf{x})_{\tilde{\tilde{\chi}}}^2 = \left[\frac{\pi}{2(\Lambda + 1)} \right]^2 + O\left(\frac{1}{\Lambda^3}\right).$$

Comparison with Perelomov & Madore

More precisely, we will compare the spatial dispersion $(\Delta \mathbf{x})^2$ of the Madore fuzzy sphere with the our $(\Delta \mathbf{x})^2$ when the representation spaces are

$$V_\Lambda := \text{span} \{ Y_\Lambda^m : -\Lambda \leq m \leq \Lambda \}$$

and

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respectively.

So, it's obvious that (definitively)

$$(\Delta \mathbf{x})_{min}^2 \leq (\Delta \mathbf{x})_{\tilde{\chi}}^2 < (\Delta \mathbf{x})_{min}^2.$$

Fourth target

If $D = 2$ and we adopt $T = \pi_{\Lambda,2}$ and as G not $SU(2)$ but its subgroup $G = U(1)$; hence $\mathcal{H}_{\Lambda,2}$ carries a *reducible* representation of G , and **COMPLETENESS** (RESOLUTION OF UNITY) is not automatic.

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One can prove that if $\phi = \sum_{m=-\Lambda}^{\Lambda} \phi_m \psi_m$, $\|\phi\| = 1$ and

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($\phi_0 \equiv \phi$); then defining $B := \int_0^{2\pi} d\alpha P_\alpha$ it turns out that $B \propto I$ if and only if $|\phi_m|$ is independent on n , which implies $|\phi_m| = 1/(2\Lambda + 1)$, but in this case

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this goes to zero as $\Lambda \rightarrow \infty$, but more slowly than the spatial dispersion of $\tilde{\chi}$ and we proved that the same applies for $D = 3$.

In $D = 3$ we choose G not $SO(4)$ but its subgroup $G = SO(3)$, and $T = \pi_\Lambda$. The $(\mathcal{H}_\Lambda, \pi_\Lambda)$ is a *reducible* representation of G , more precisely the direct sum of the irreducible representations (V_l, π_l) , $l = 0, \dots, \Lambda$, therefore completeness and resolution of unity are not automatic.

In $D = 3$ we choose G not $SO(4)$ but its subgroup $G = SO(3)$, and $T = \pi_\Lambda$. The $(\mathcal{H}_\Lambda, \pi_\Lambda)$ is a *reducible* representation of G , more precisely the direct sum of the irreducible representations (V_l, π_l) , $l = 0, \dots, \Lambda$, therefore completeness and resolution of unity are not automatic. Consider for simplicity a unit vector of the form $\phi = \sum_{l=0}^\Lambda \phi_l \psi_l^l$, and for $g \in G$ let

$$\phi_g := \pi_\Lambda(g)\phi, \quad P_g := \phi_g \langle \phi_g, \cdot \rangle \quad (18)$$

$(\phi_l \equiv \phi)$. The system $A := \{\phi_g\}_{g \in G}$ is complete provided $\phi_l \neq 0$ for all l (then it is also overcomplete). Defining $B := \int_{SO(3)} d\mu(g) P_g$ one finds that B is proportional to the identity only if $|\phi_l|^2$ is independent of l and therefore (since $\|\phi\| = 1$) if $|\phi_l|^2 = 1/(\Lambda+1)$. Setting $\phi_l = e^{i\beta_l}/\sqrt{\Lambda+1}$ ($\beta_l \in \mathbb{R}$) we find the following resolutions of the identity, parametrized by $\beta \in (\mathbb{R}/2\pi\mathbb{Z})^{\Lambda+1}$:

$$I = \frac{\Lambda+1}{2\pi^3} \int_{SO(3)} d\mu(g) P_g^\beta, \quad P_g^\beta := \psi_g^\beta \langle \psi_g^\beta, \cdot \rangle, \quad \psi_g^\beta := \sum_{m=-\Lambda}^\Lambda \frac{e^{i\beta_l}}{\sqrt{\Lambda+1}} \pi_\Lambda(g) \psi_l^l.$$

Appendix

Another possibility is to minimize the variance of $\pi_{\Lambda,2} [\mathbf{L}^2]$, but one can easily show that in this case the “coherent states” (the ones minimizing that variance) are ψ_{Λ} and $\psi_{-\Lambda}$, which are not meaningful in the high energy limit $\Lambda \rightarrow +\infty$.

Appendix

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Incidentally, some authors consider also two definitions of sets of optimally localized states on the spin sphere alternative to the one adopted by Perelomov: the set of “intelligent states”, that saturate the uncertainty relation $\Delta L_1 \Delta L_2 \geq |\langle L_3 \rangle|/2$, and the set of “minimum uncertainty states”, for which $\Delta L_1 \Delta L_2$ has a local minimum (note that then in general $\Delta L_1 \Delta L_3$, $\Delta L_2 \Delta L_3$ are not minimized). But neither one is invariant under arbitrary rotation, in contrast with the definition of Perelomov and of the present work; one can easily show that these states are “fewer” than the points of S^2 , i.e cannot be put in one-to-one correspondence with the points of S^2 , but just of a finite number of lines on S^2 .